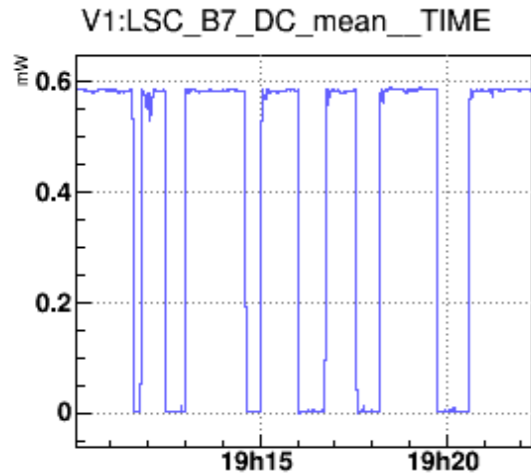
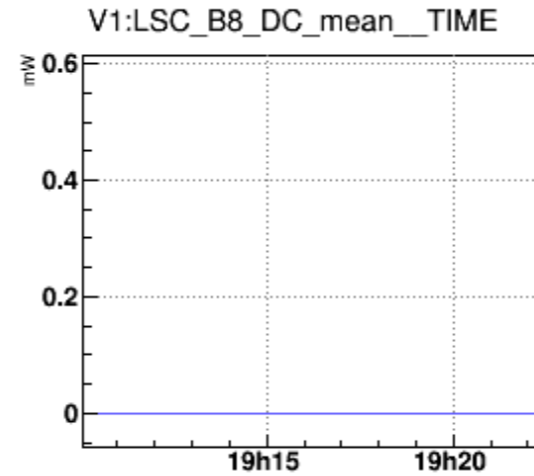


North arm locks-unlocks

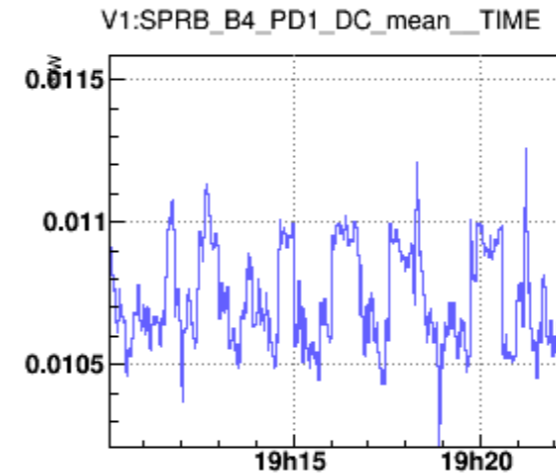
dataDisplay v10r8 : started by capocasa on Nov 18 2017 11:11:49 UTC



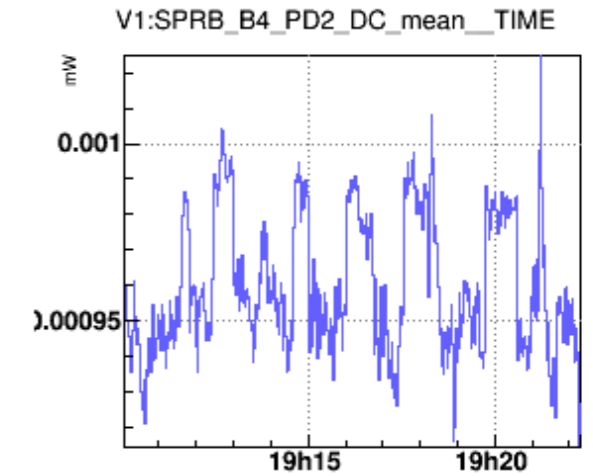
1194981024.0000 : Nov 17 2017 19:10:06 UTC



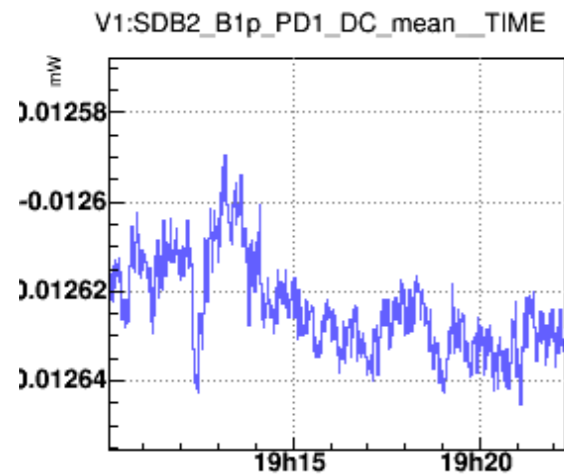
1194981024.0000 : Nov 17 2017 19:10:06 UTC



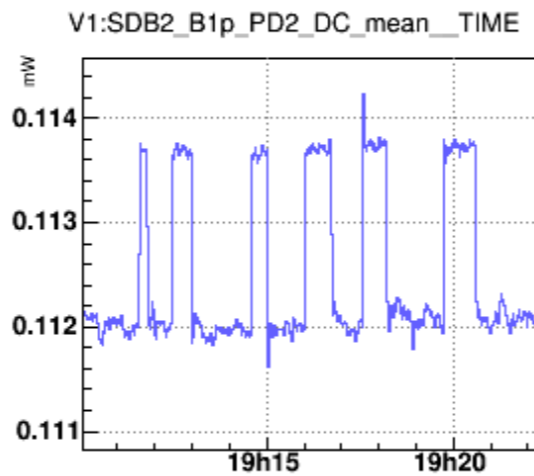
1194981024.0000 : Nov 17 2017 19:10:06 UTC



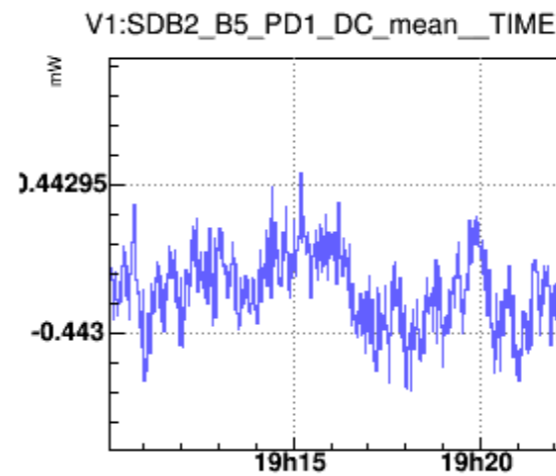
1194981024.0000 : Nov 17 2017 19:10:06 UTC



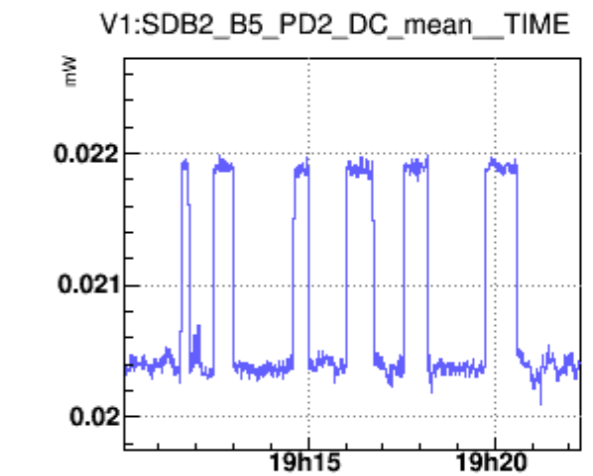
1194981024.0000 : Nov 17 2017 19:10:06 UTC



1194981024.0000 : Nov 17 2017 19:10:06 UTC

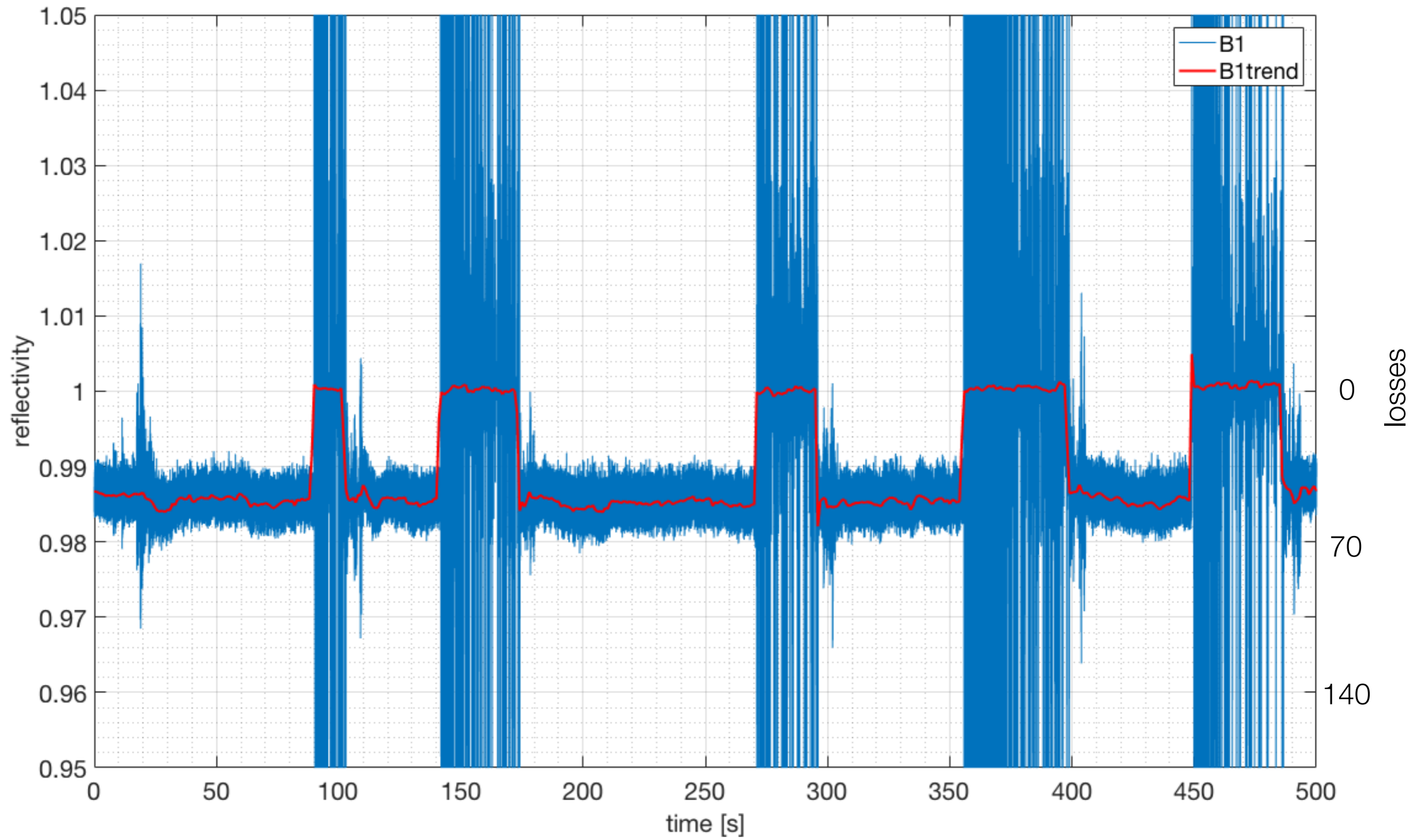


1194981024.0000 : Nov 17 2017 19:10:06 UTC



1194981024.0000 : Nov 17 2017 19:10:06 UTC

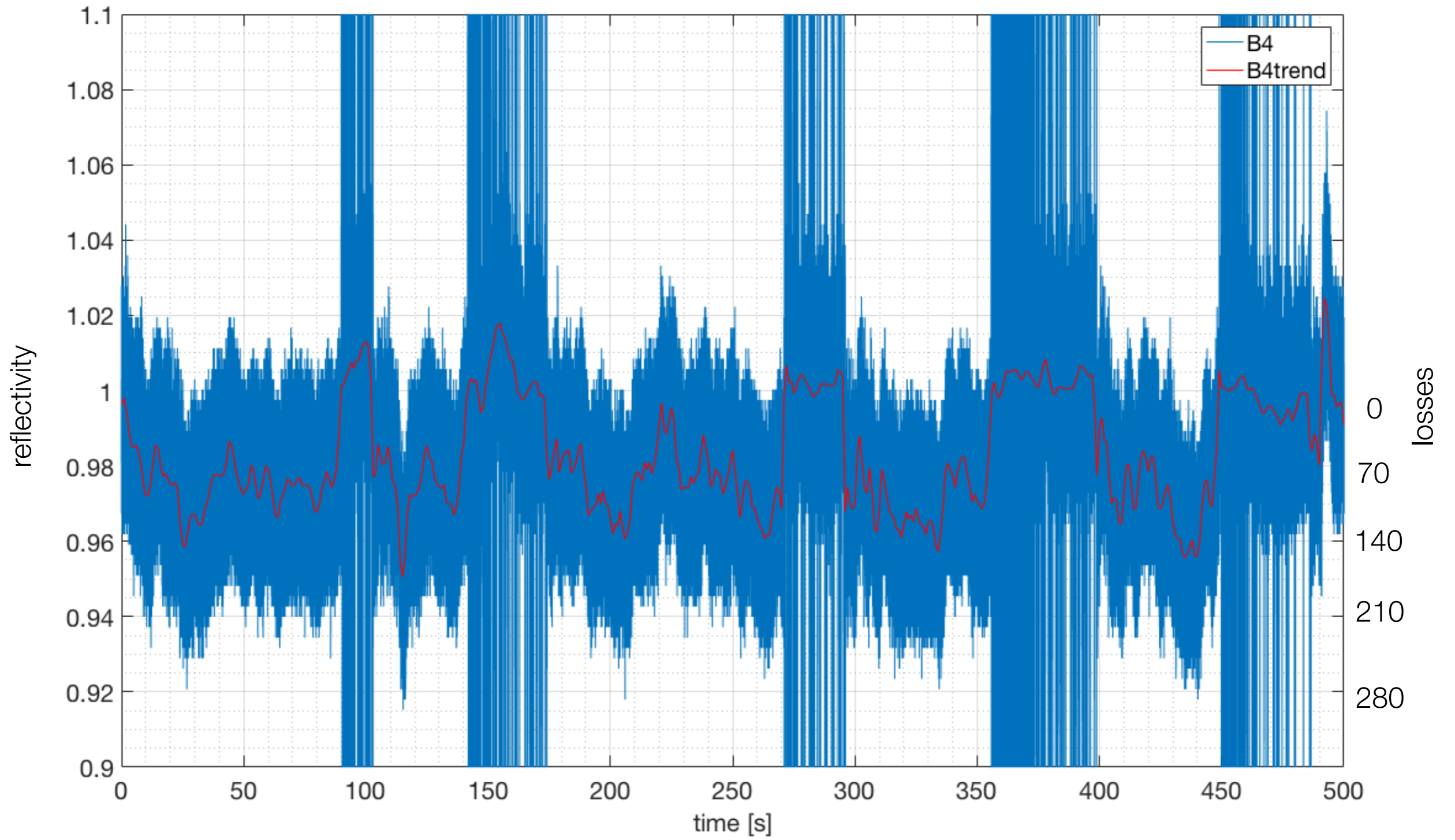
B1p_PD2 North arm



GPS = 1198941024

offset = $-3.4e-4$

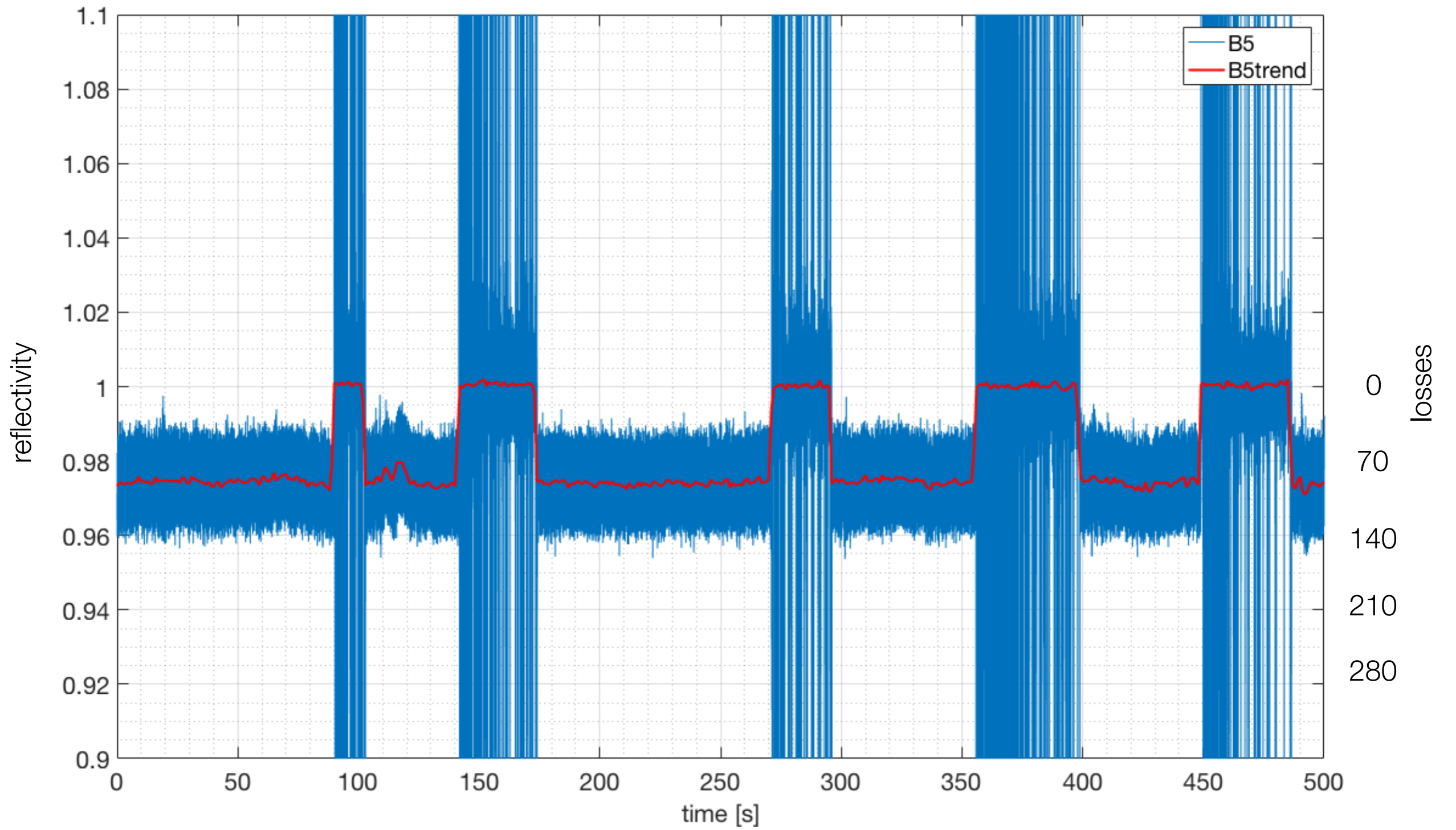
B4_PD1 North arm



GPS = 1198941024

offset = -1.1×10^{-4}

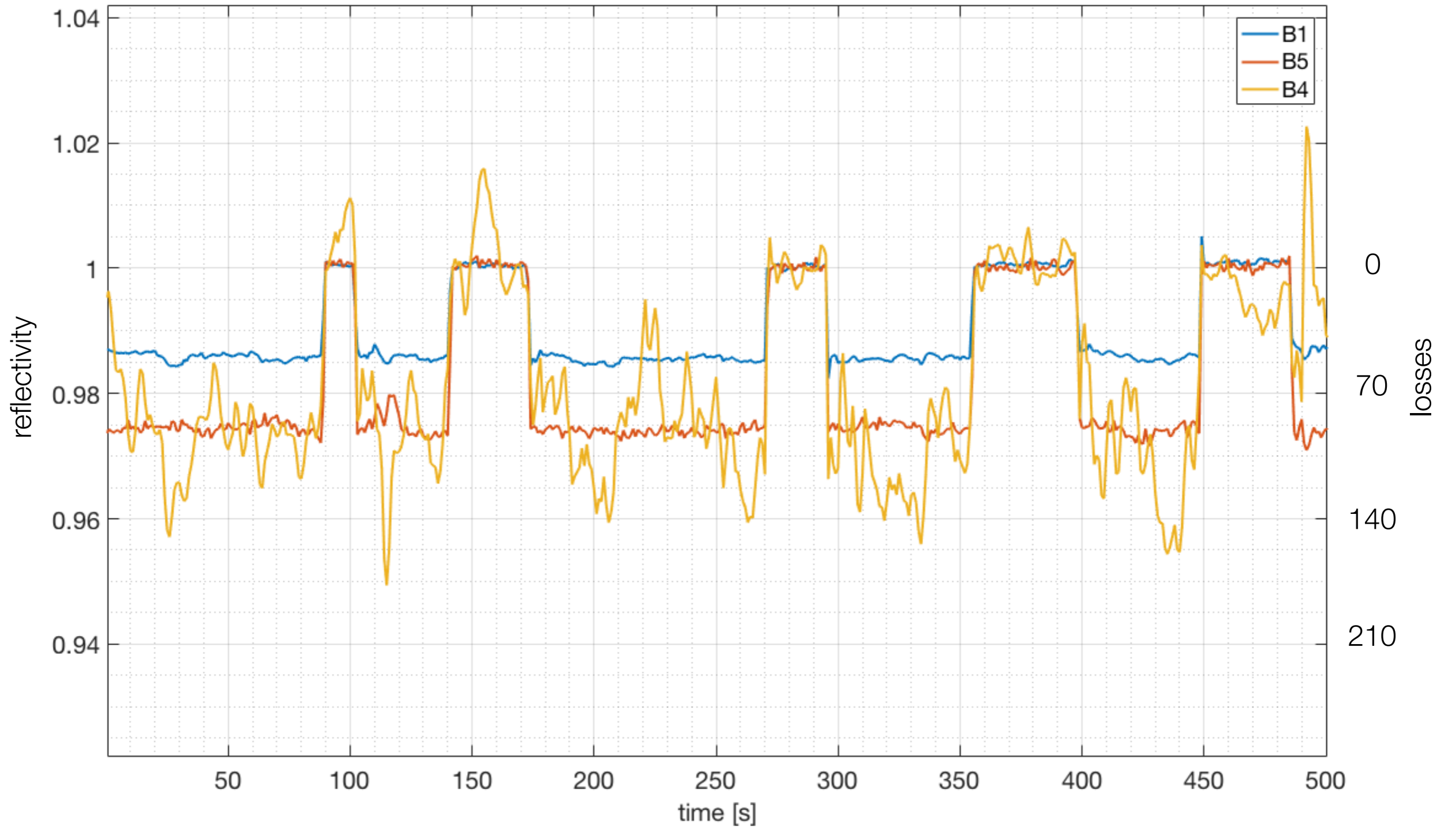
B5_PD2 North arm



GPS = 1198941024

offset = 9e-3

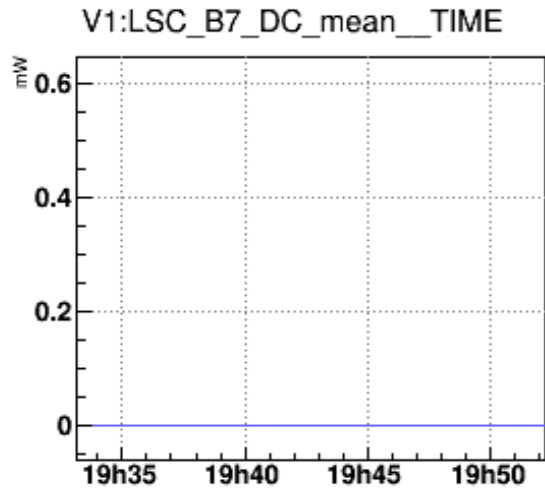
North arm summary



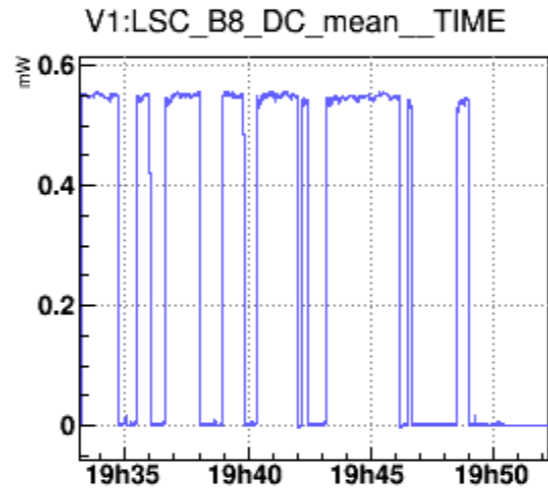
GPS = 1198941024

West arm locks-unlocks

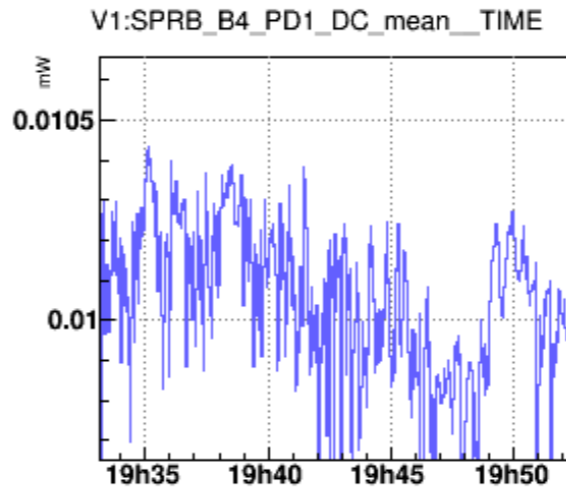
dataDisplay v10r8 : started by capocasa on Nov 20 2017 11:33:46 UTC



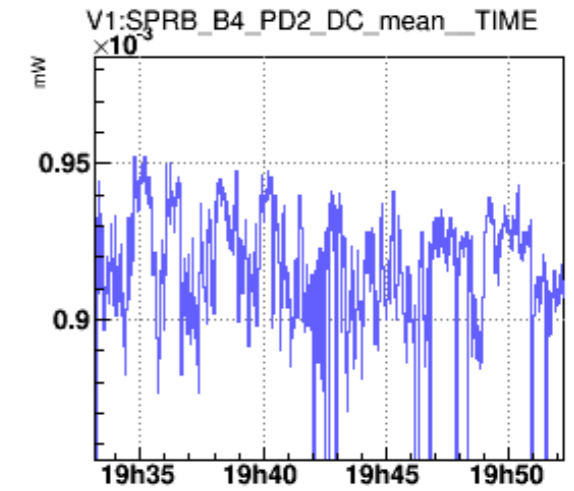
1194982409.0000 : Nov 17 2017 19:33:11 UTC



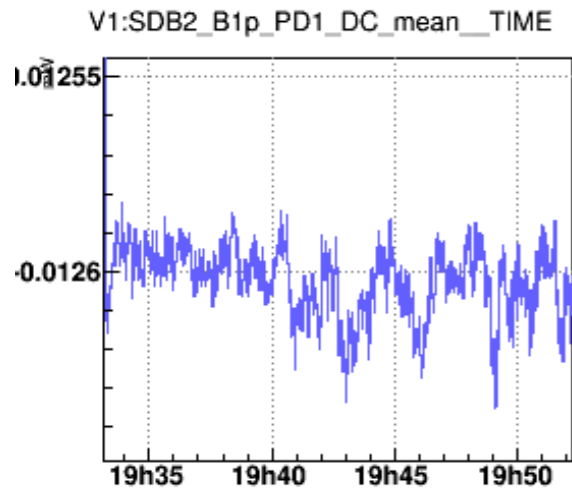
1194982409.0000 : Nov 17 2017 19:33:11 UTC



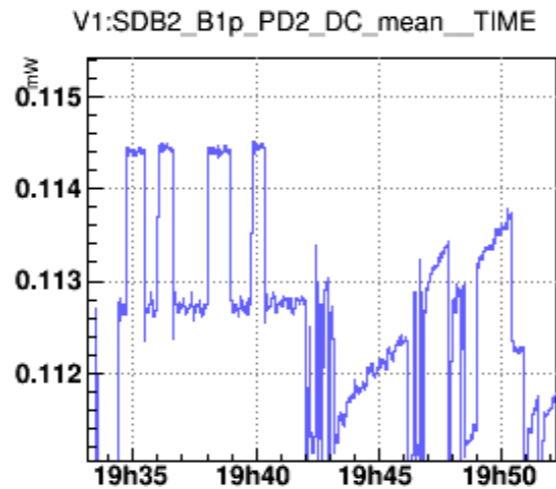
1194982409.0000 : Nov 17 2017 19:33:11 UTC



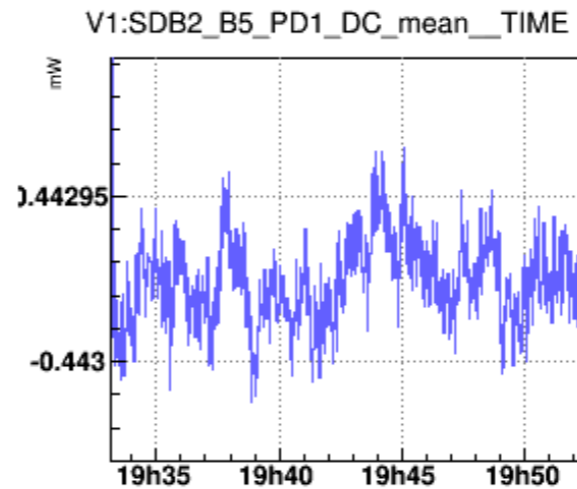
1194982409.0000 : Nov 17 2017 19:33:11 UTC



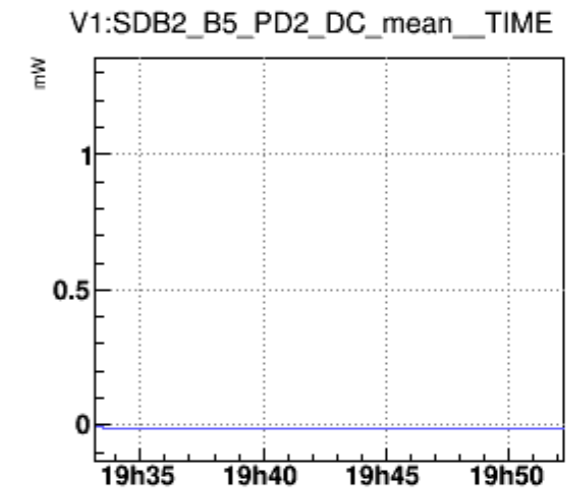
1194982409.0000 : Nov 17 2017 19:33:11 UTC



1194982409.0000 : Nov 17 2017 19:33:11 UTC

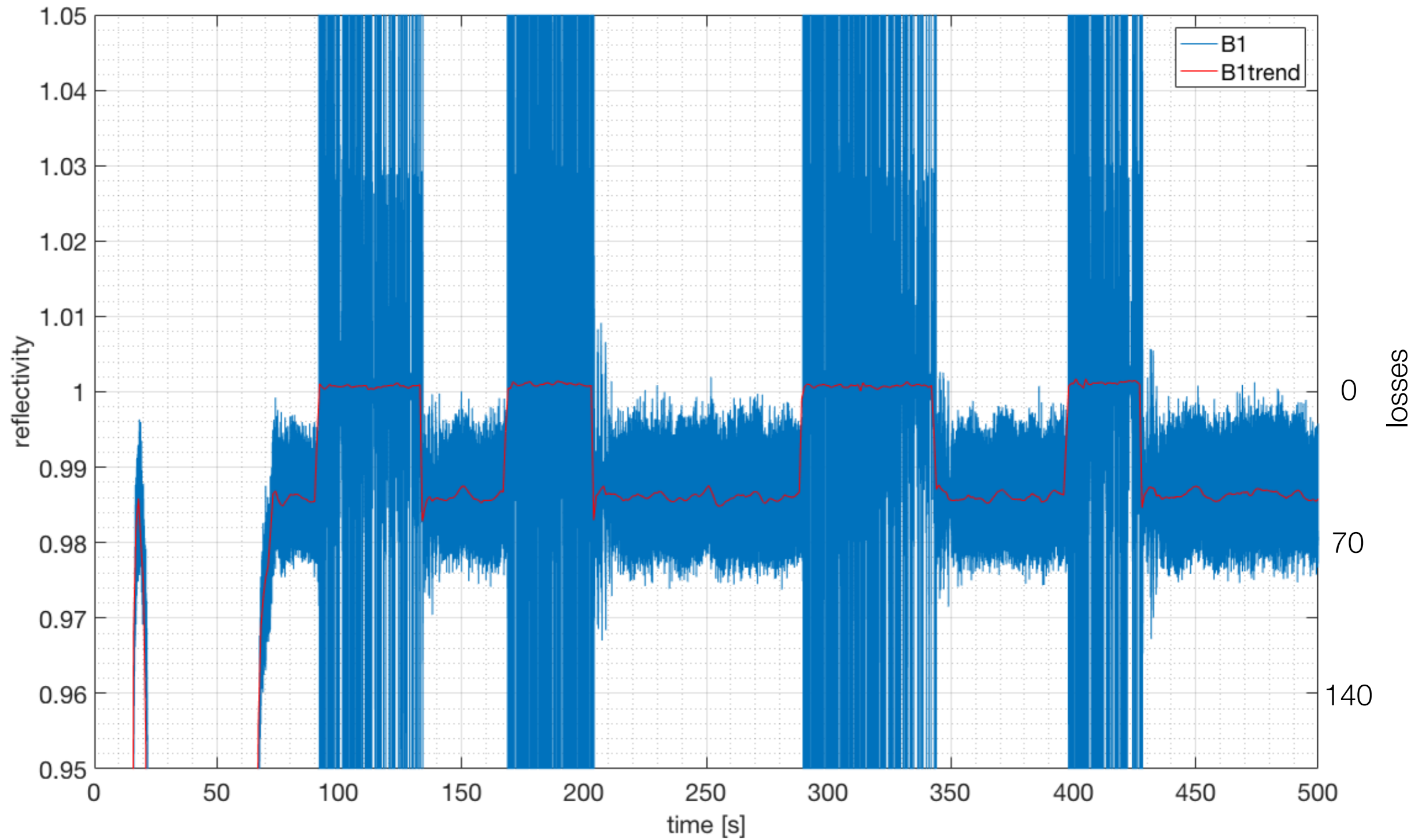


1194982409.0000 : Nov 17 2017 19:33:11 UTC



1194982409.0000 : Nov 17 2017 19:33:11 UTC

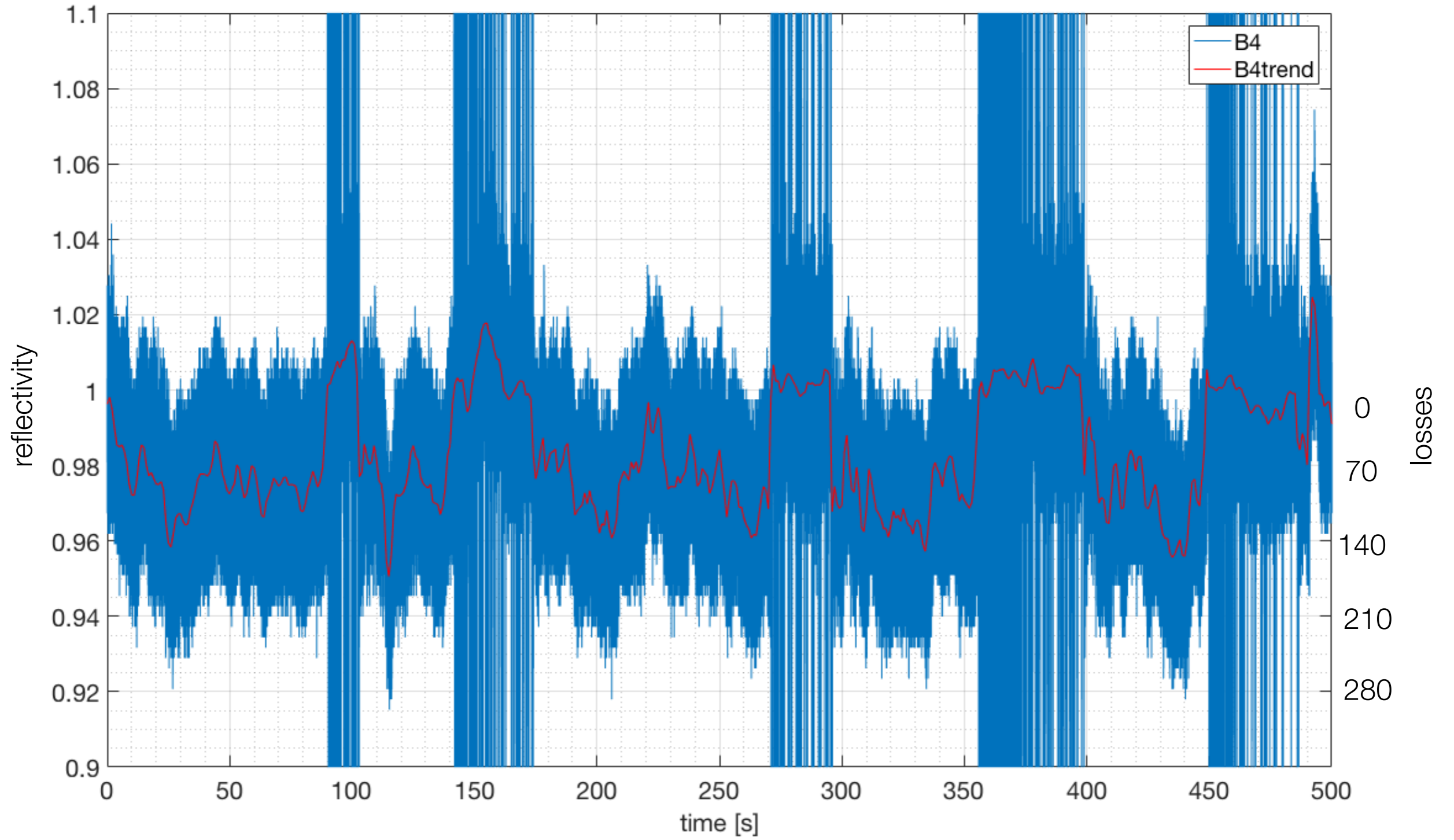
B1p_PD2 West arm



GPS = 1198942410

offset = $-3.4e-4$

B4_PD1 West arm



GPS = 1198942410

offset = $-1.1e-4$